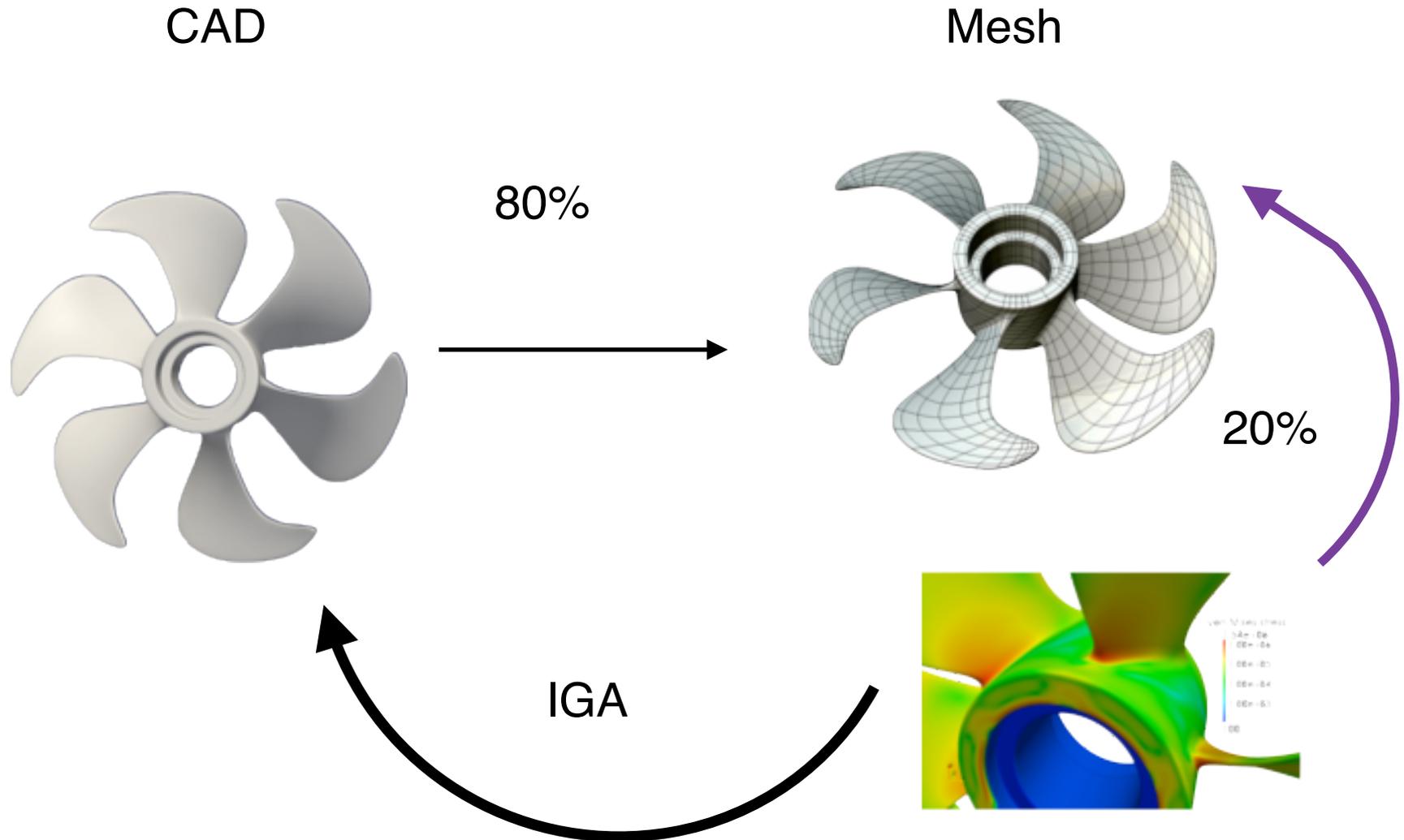


# **An introduction to isogeometric analysis**

Vinh Phu NGUYEN

# How Isogeometric analysis was born?



# B-splines basis functions

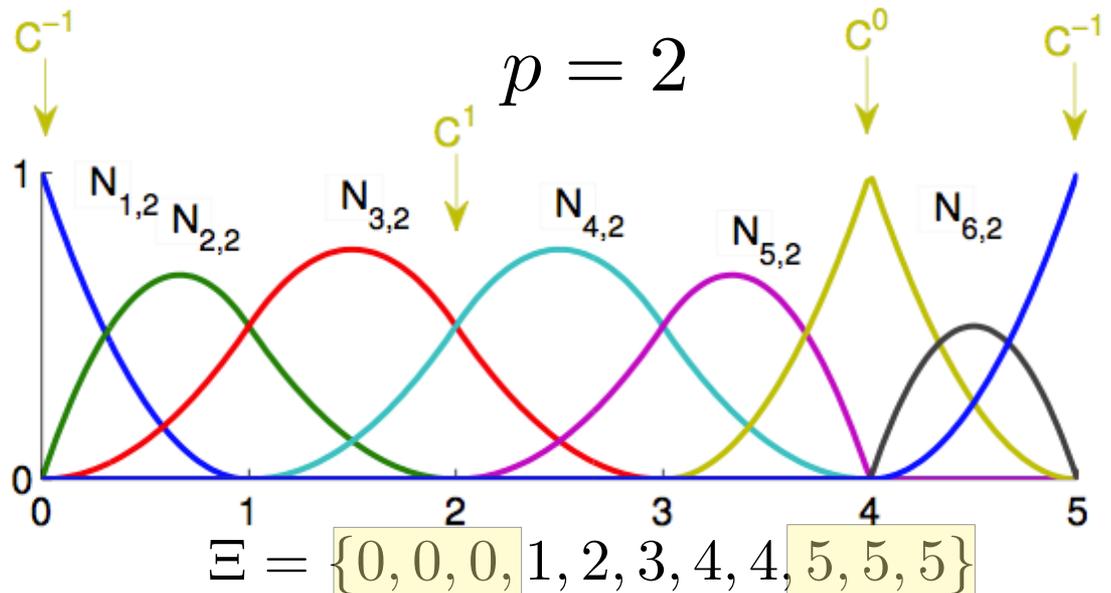
$$\Xi = \{\xi_1, \xi_2, \dots, \xi_{n+p+1}\} \quad \text{knot vector}$$

$$N_{i,0}(\xi) = \begin{cases} 1 & \text{if } \xi_i \leq \xi < \xi_{i+1} \\ 0 & \text{otherwise} \end{cases} \quad \text{\sigma}$$

$$N_{i,p}(\xi) = \frac{\xi - \xi_i}{\xi_{i+p} - \xi_i} N_{i,p-1}(\xi) + \frac{\xi_{i+p+1} - \xi}{\xi_{i+p+1} - \xi_{i+1}} N_{i+1,p-1}(\xi)$$

## Properties

- Partition of Unity
- Linear independence
- Non-negativity
- $C^{p-m}$  continuity
- Not interpolants



# B-splines curves/surfaces

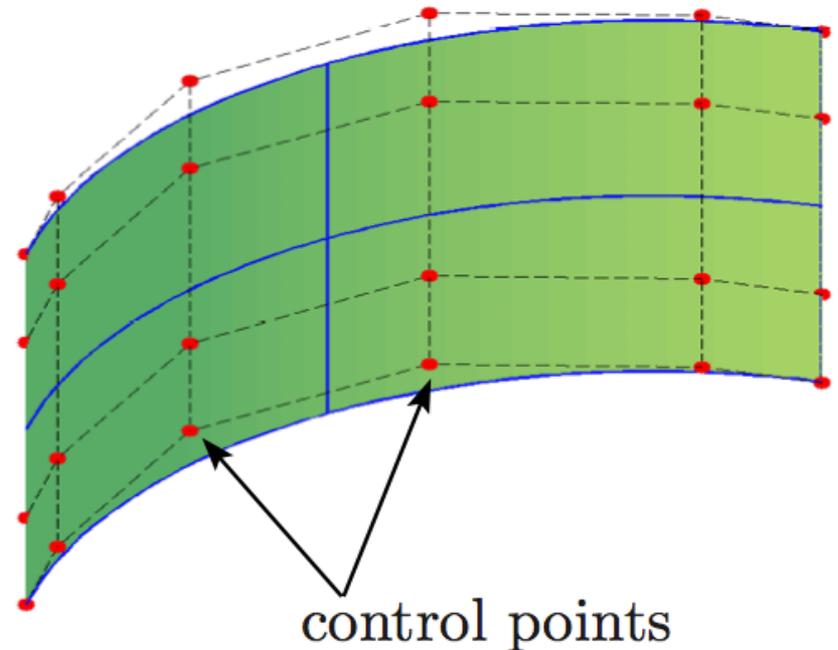
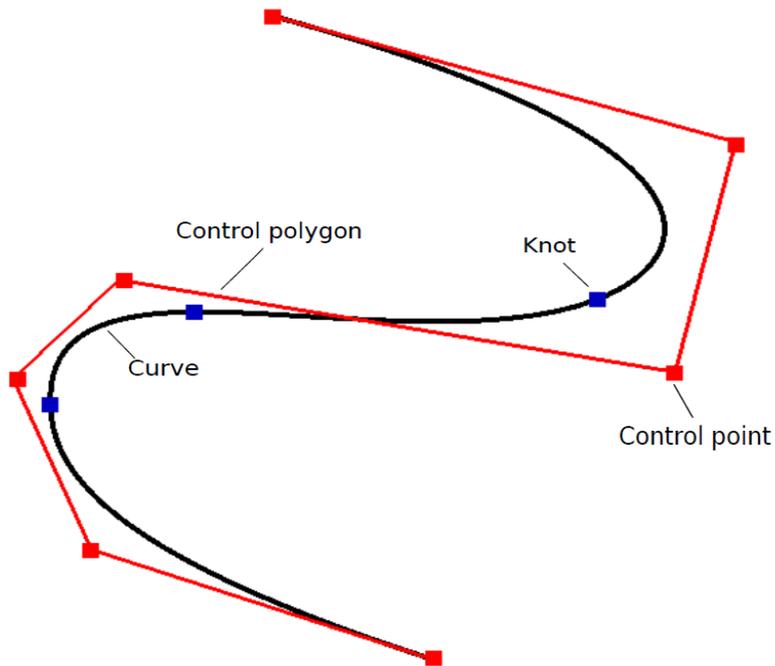
$$\Xi = \{\xi_1, \xi_2, \dots, \xi_{n+p+1}\}$$

$$\Xi^1 = \{\xi_1, \xi_2, \dots, \xi_{n+p+1}\}$$

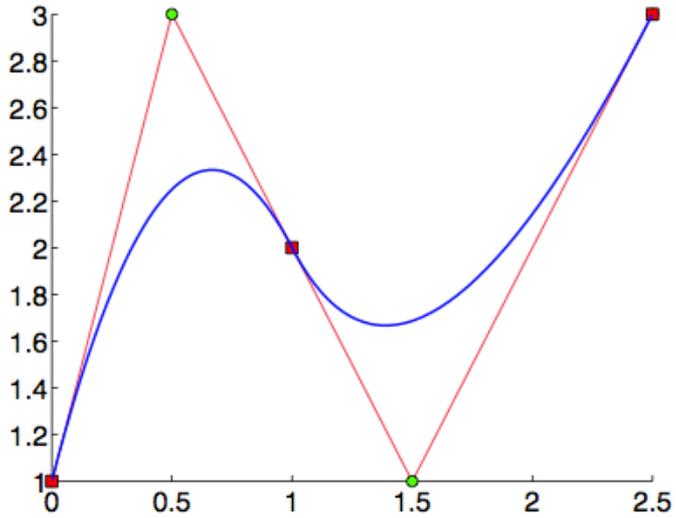
$$\Xi^2 = \{\eta_1, \eta_2, \dots, \eta_{m+q+1}\}$$

$$\mathbf{C}(\xi) = \sum_{i=1}^n N_{i,p}(\xi) \mathbf{B}_i$$

$$\mathbf{S}(\xi, \eta) = \sum_{i=1}^n \sum_{j=1}^m N_{i,p}(\xi) M_{j,q}(\eta) \mathbf{B}_{ij}$$



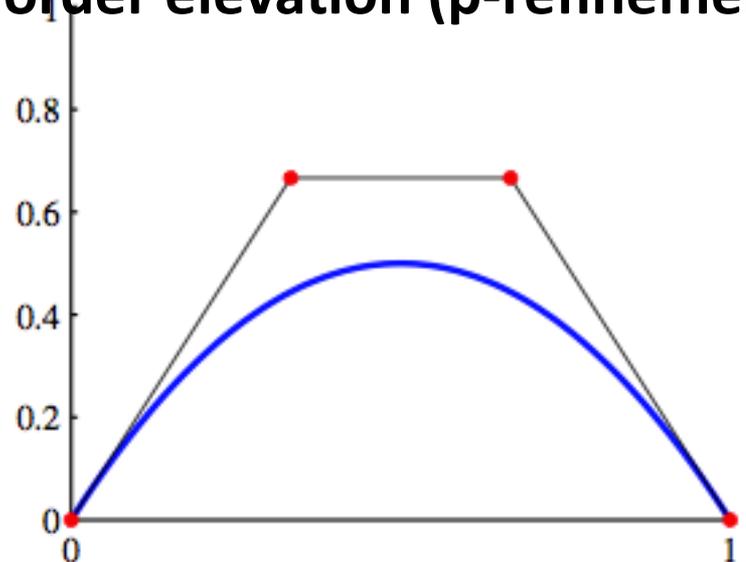
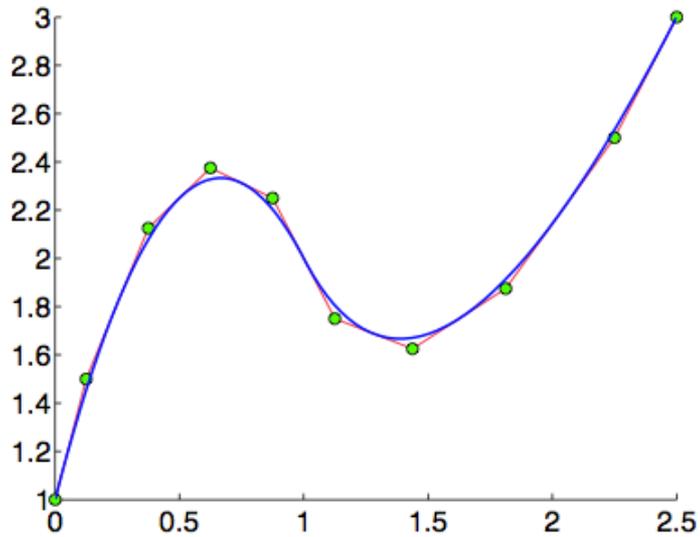
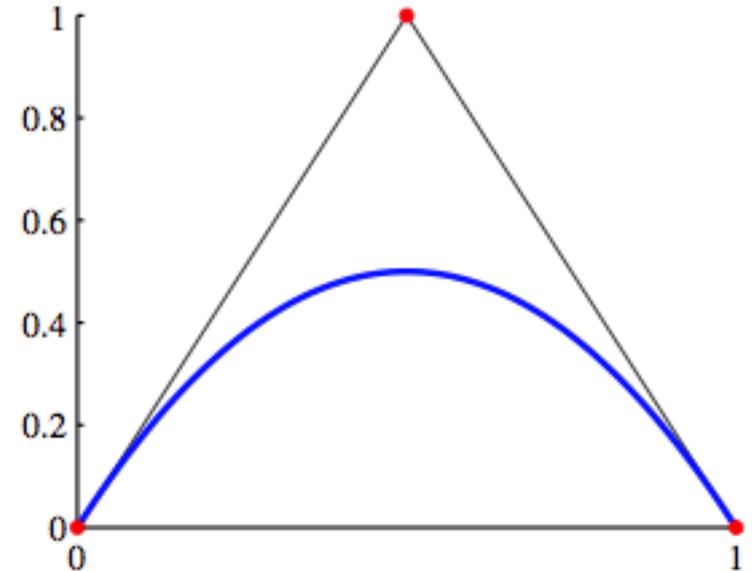
# Enriching B-splines



**knot insertion (h-refinement)**

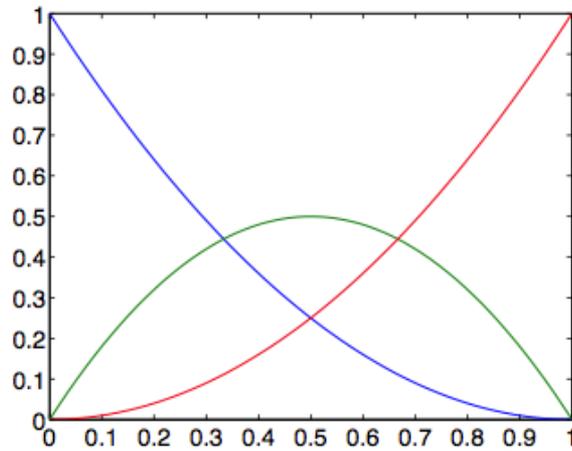
**+**

**order elevation (p-refinement)**

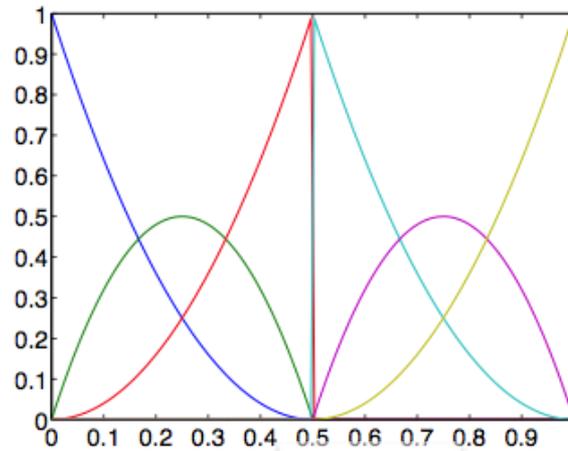


*does not change B-splines geometrically/parametrically*

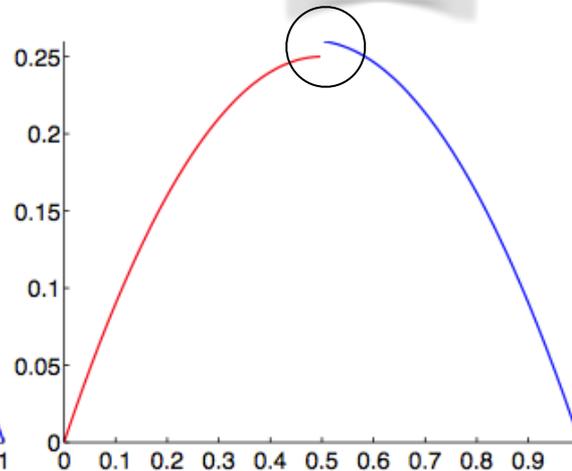
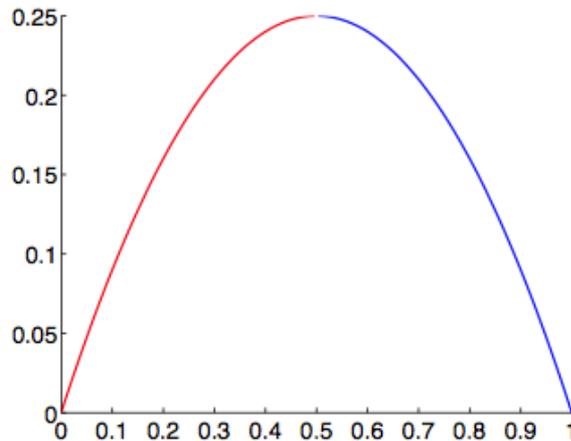
# Knot insertion to create discontinuities



(a)  $\Xi = \{0, 0, 0, 1, 1, 1\}$



(b)  $\Xi' = \{0, 0, 0, 0.5, 0.5, 0.5, 1, 1, 1\}$

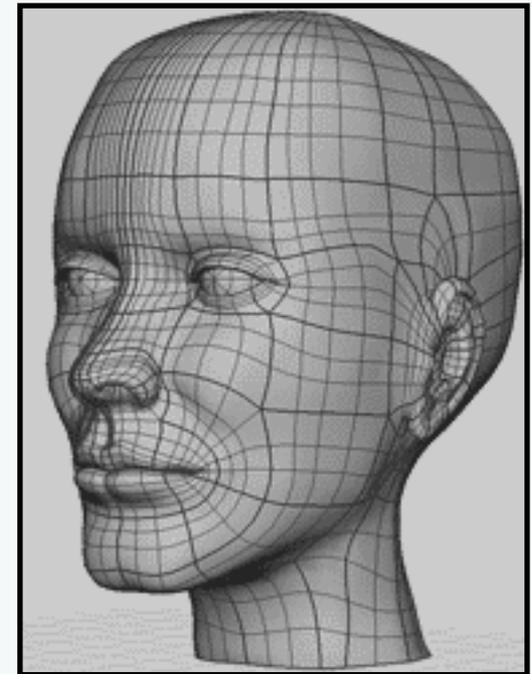
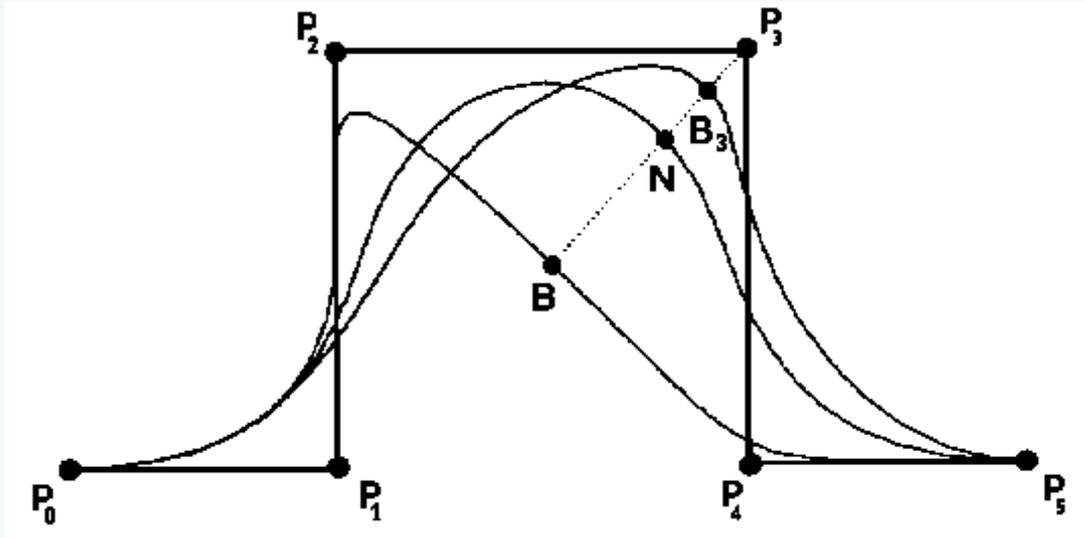


$$p = 2$$

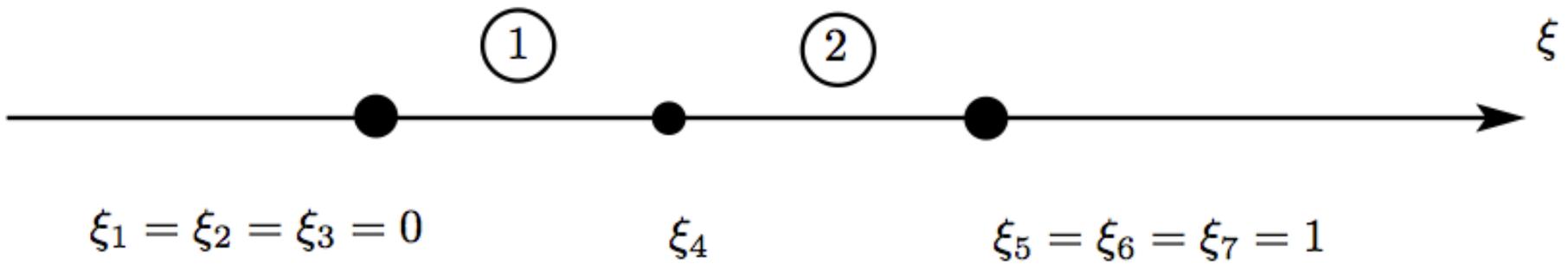
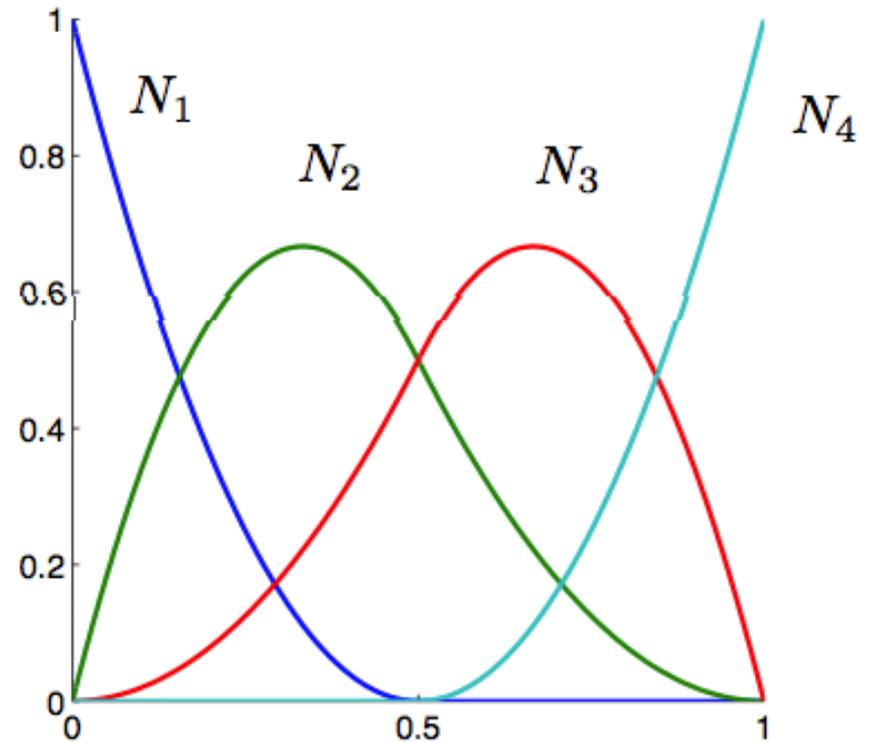
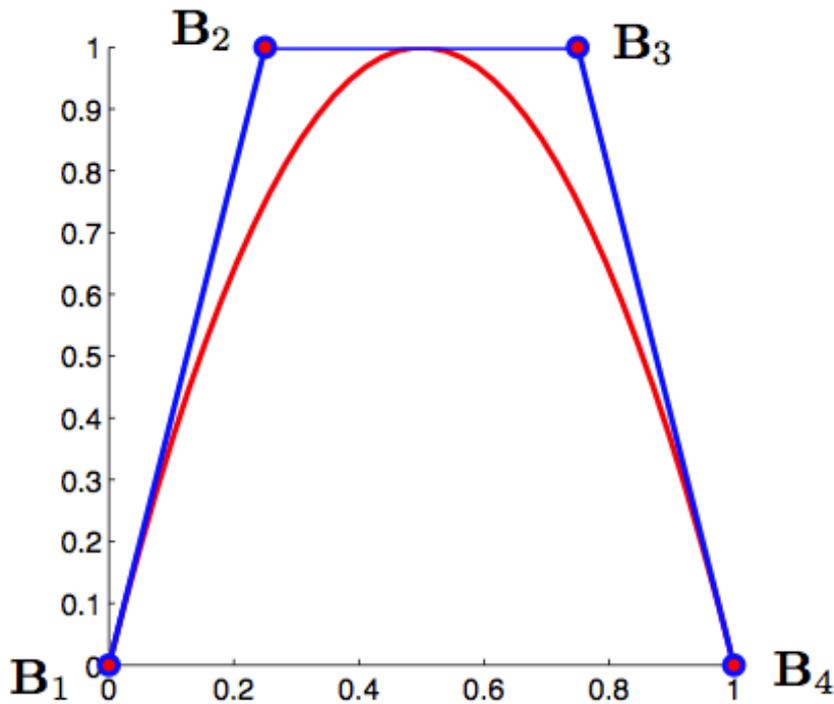
Crack modeling and composite laminates (Layer wise theory, Z. Gurdal)

# Non Uniform Rational B-splines (NURBS)

$$R_{i,p}(\xi) = \frac{N_{i,p}(\xi)w_i}{W(\xi)} = \frac{N_{i,p}(\xi)w_i}{\sum_{j=1}^n N_{j,p}(\xi)w_j},$$



# One dimensional IGA FEM



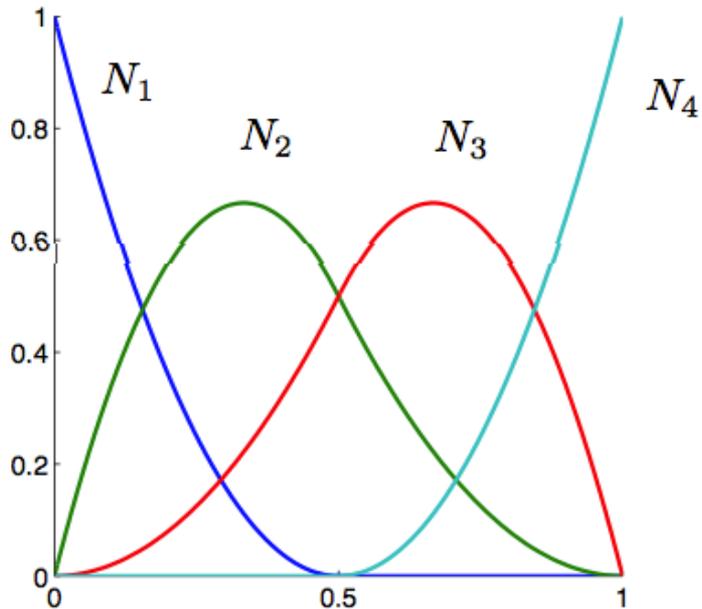
$$\xi_1 = \xi_2 = \xi_3 = 0$$

$$\xi_4$$

$$\xi_5 = \xi_6 = \xi_7 = 1$$

$$\Xi = \{0, 0, 0, 1/2, 1, 1, 1\}$$

# One dimensional IGA FEM



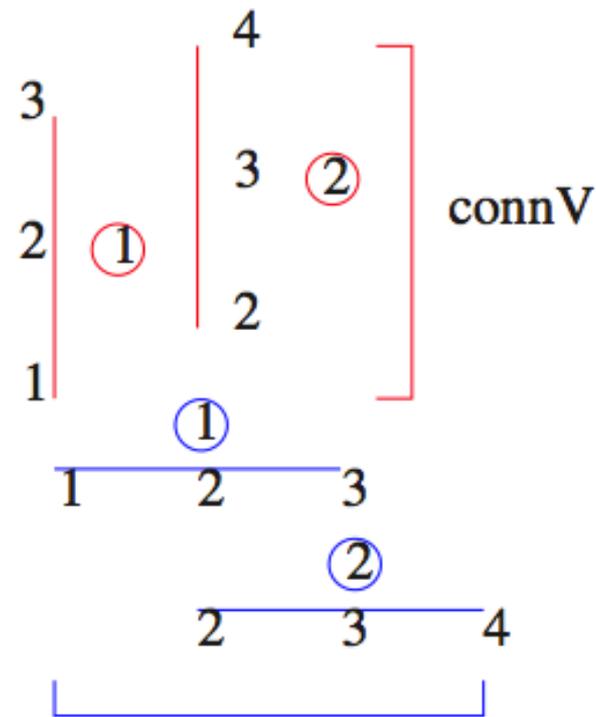
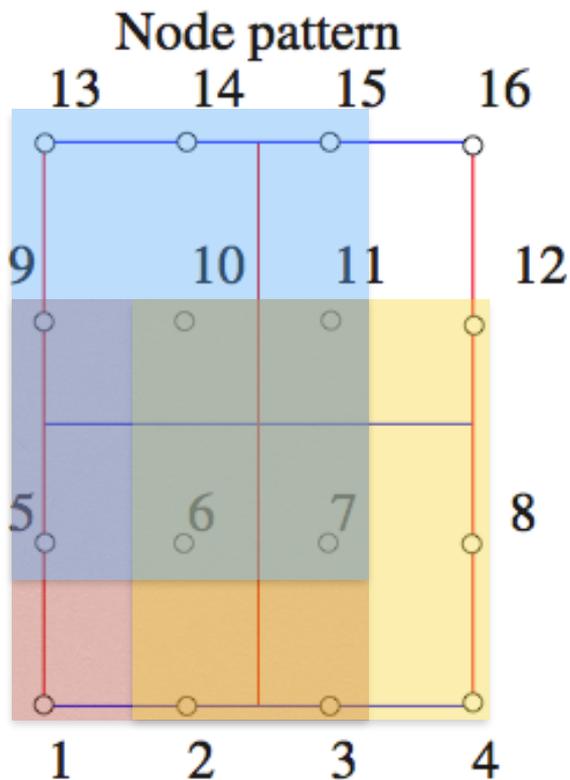
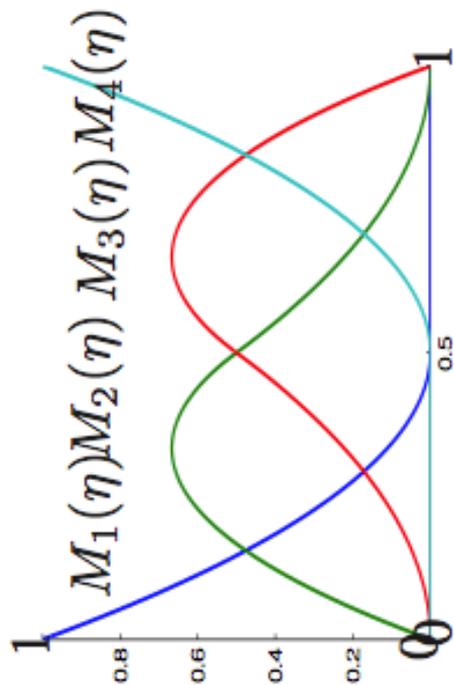
Isoparametric

$$x = N_I x_I$$

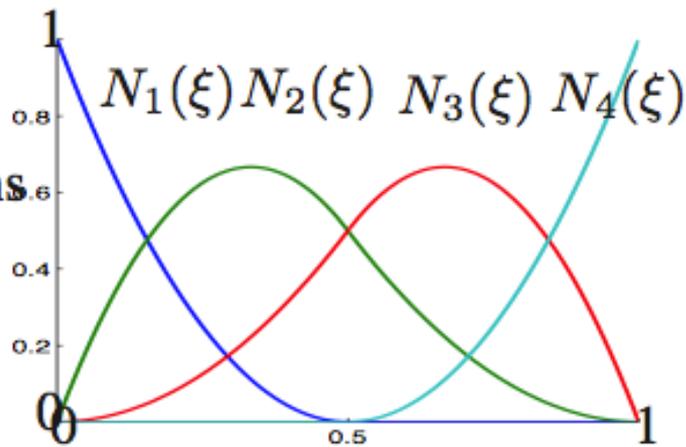
$$u = N_I u_I$$

element	range	non-zero basis	dofs	control points
1	$[\xi_3, \xi_4]$	$N_1, N_2, N_3$	$u_1, u_2, u_3$	$\mathbf{B}_1, \mathbf{B}_2, \mathbf{B}_3$
2	$[\xi_4, \xi_5]$	$N_2, N_3, N_4$	$u_2, u_3, u_4$	$\mathbf{B}_2, \mathbf{B}_3, \mathbf{B}_4$

# Two dimensional IGA FEM



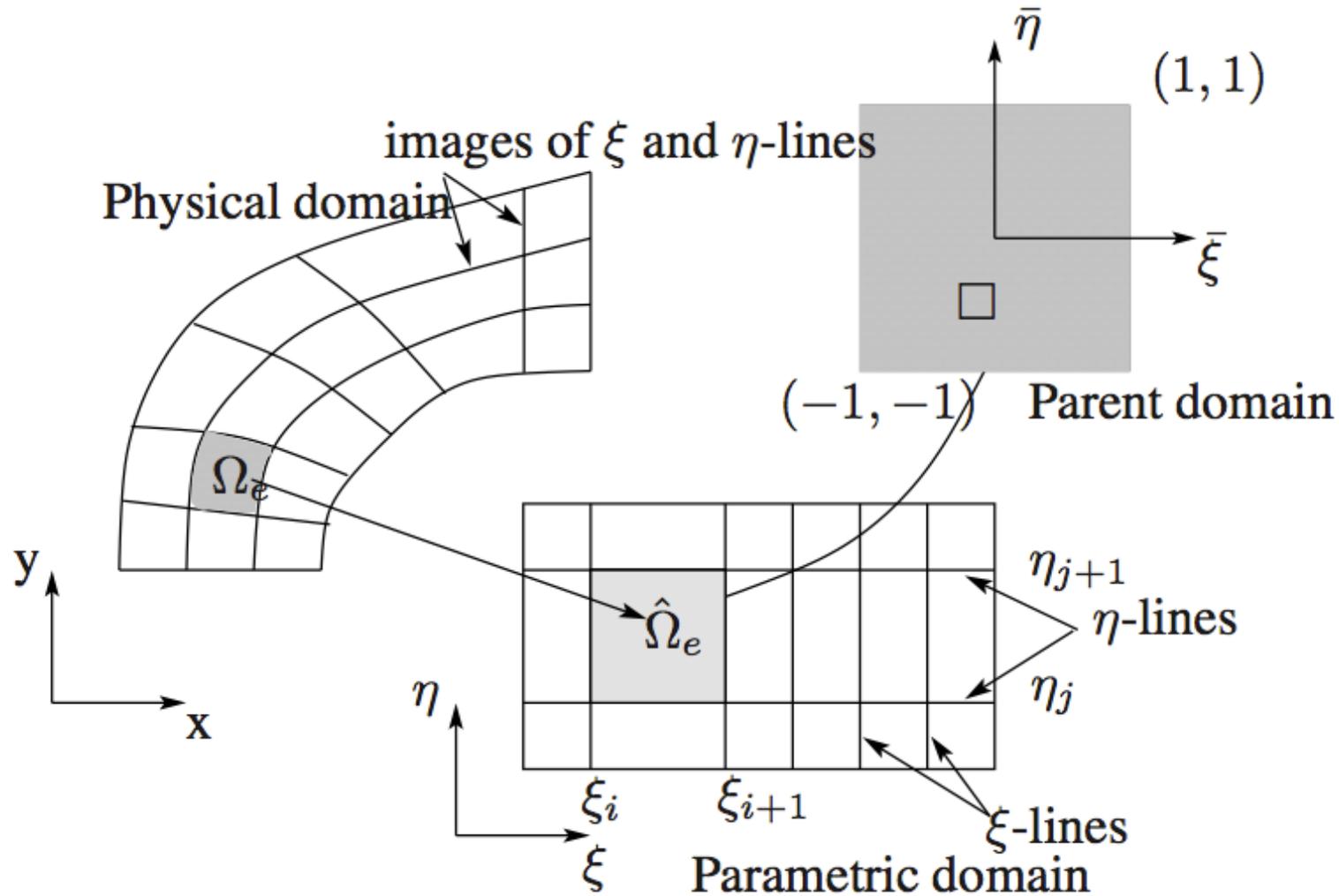
Basis functions



$$\Xi = \{0, 0, 0, 0.5, 1, 1, 1\}$$

$$\mathcal{H} = \{0, 0, 0, 0.5, 1, 1, 1\}$$

# Numerical integration



# Examples

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## MIGFEM



- quick prototyping
- tutorial codes

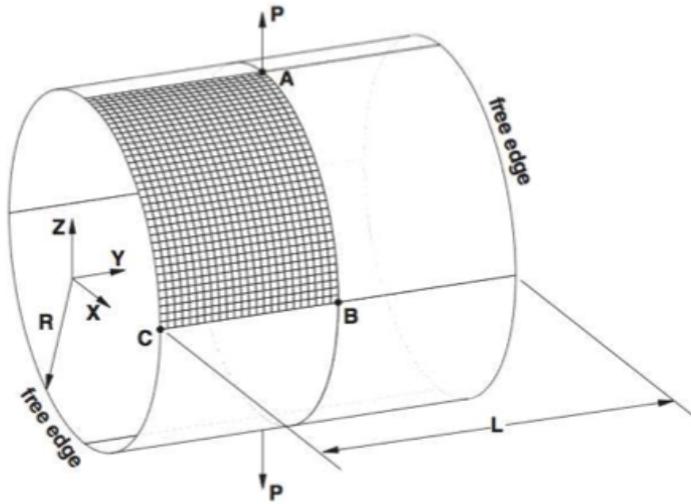
- open source Matlab Isogeometric (X)FEM
- 2D/3D solid mechanics with geometry nonlinearities
- 2D XIGA for LEFM and material interfaces
- Structural mechanics: beam, plate, shells (large deformation)
- <http://sourceforge.net/projects/cmcodes/>

## jem-jive (Linux, Mac OS, Windows)

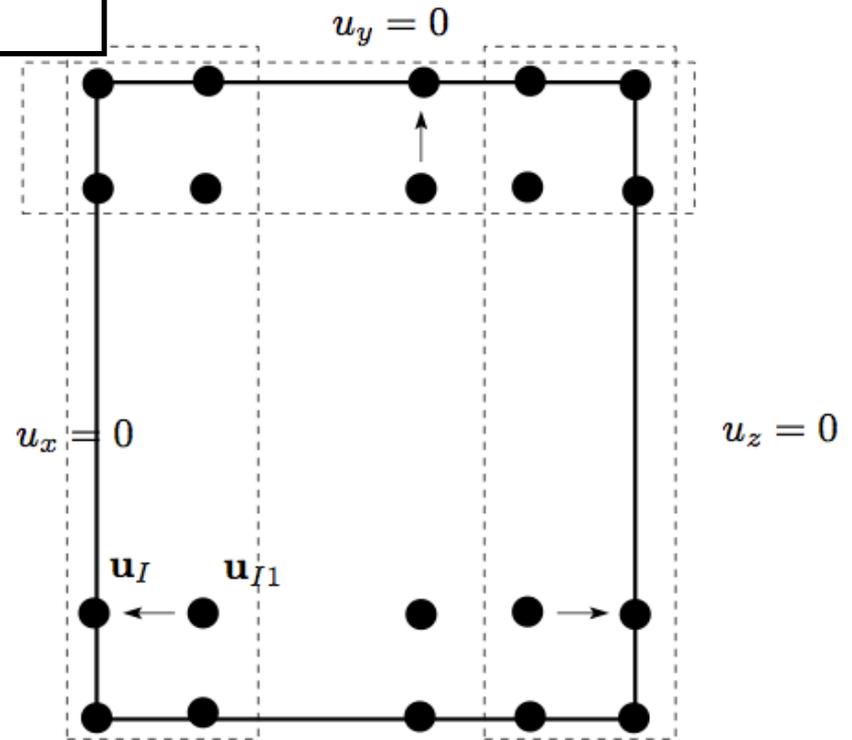
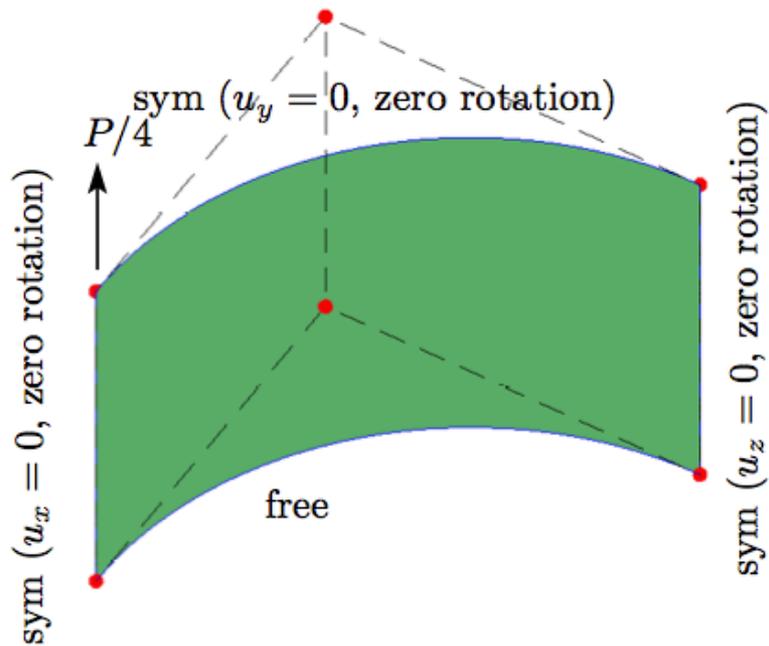
- commercial C++ toolkit for PDEs
- not a general purpose FE package
- tailor made applications, suitable for researchers
- apps: XFEM, dG, IGA, DEM, FVM etc.
- support parallel computing
- implements useful concepts available in other programming languages--Java, Fortran 90, Matlab and C#
- tensor class: useful to evaluating complex constitutive models
- [http://www.dynaflow.com/en\\_GB/jive.html](http://www.dynaflow.com/en_GB/jive.html)



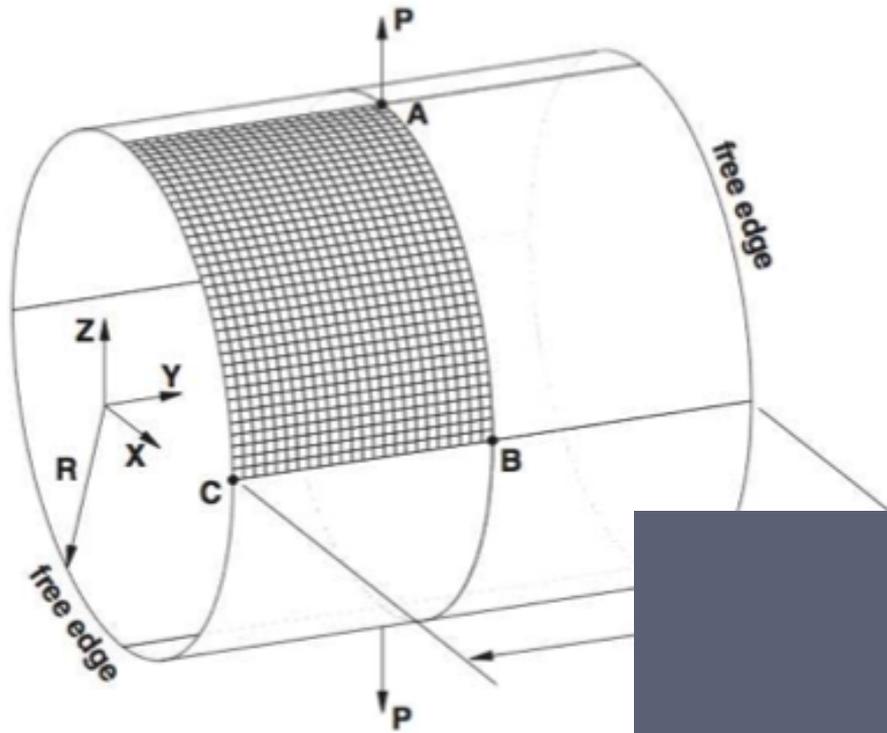
# IGA rotation free nonlinear shell



$E = 10.5 \times 10^6$   
 $\nu = 0.3125$   
 $R = 4.953$   
 $L = 10.35$   
 $h = 0.094$   
 $P_{\max} = 40,000$



# IGA rotation free nonlinear shell



$$E = 10.5 \times 10^6$$

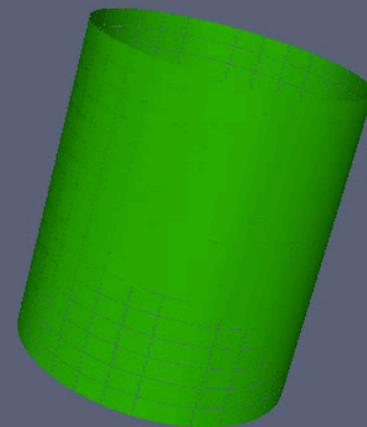
$$\nu = 0.3125$$

$$R = 4.953$$

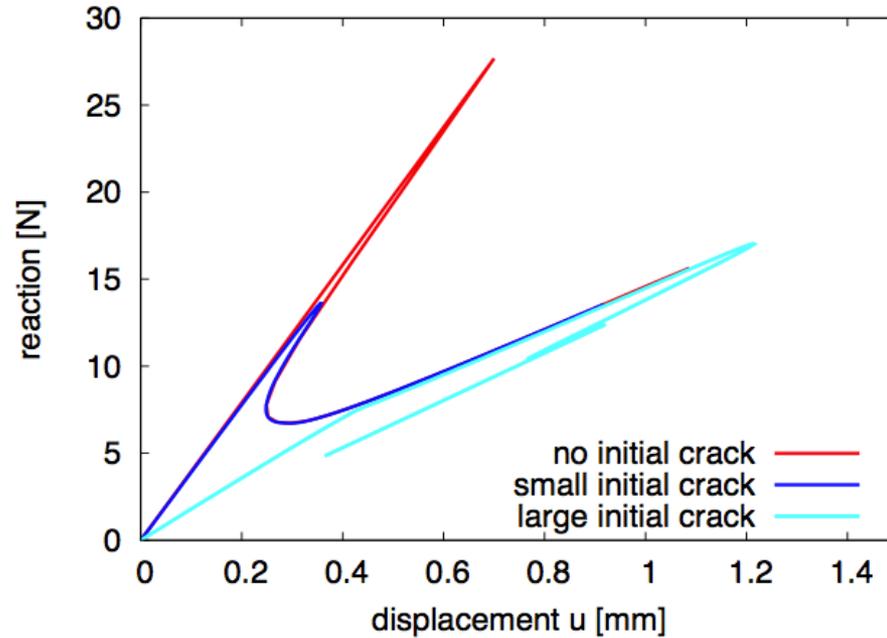
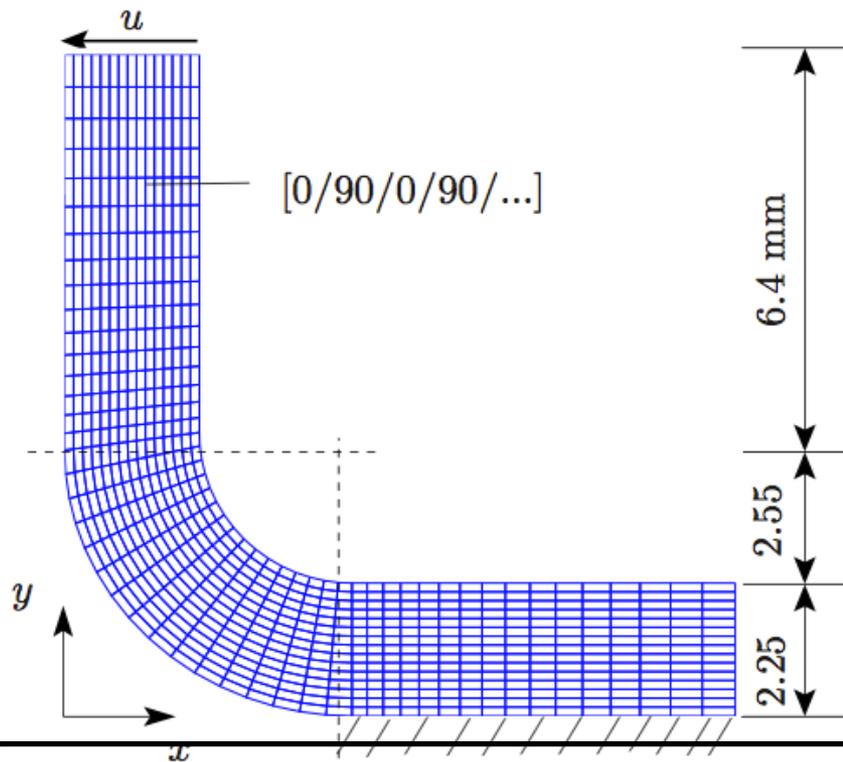
$$L = 10.35$$

$$h = 0.094$$

$$P_{\max} = 40,000$$



# Isogeometric cohesive elements: 2D example

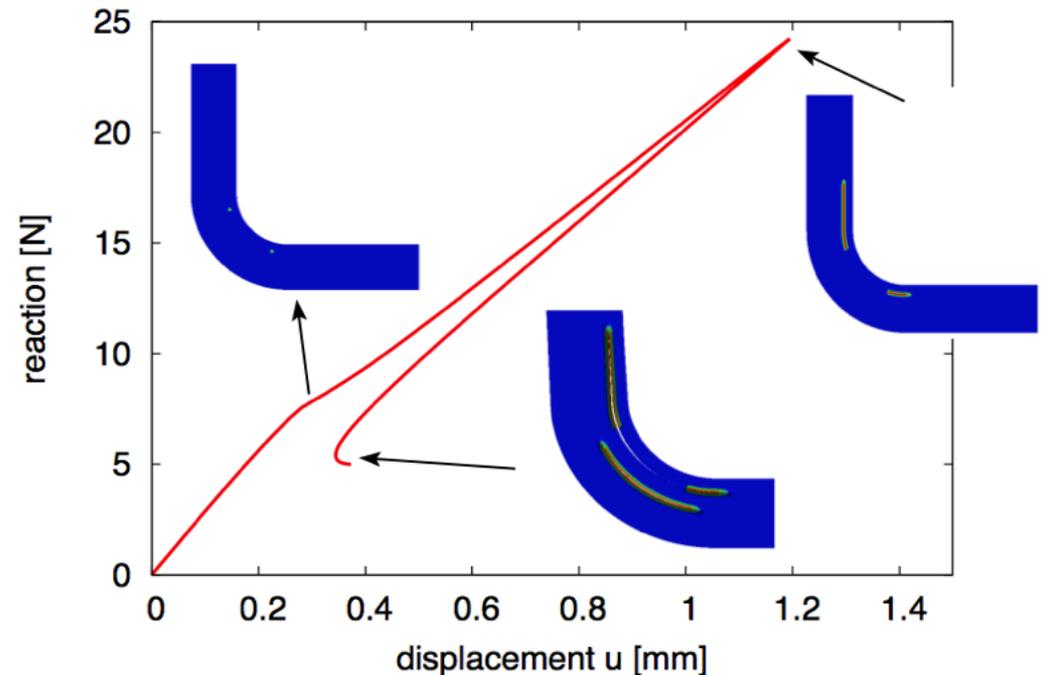


- exact geometry by NURBS
- It is straightforward to vary
  - (1) number of plies and
  - (2) # of interface elements:
- Suitable for parameter studies/design
- Cohesive law: bilinear law of Turon et al. 2006

# Isogeometric cohesive elements: 2D example

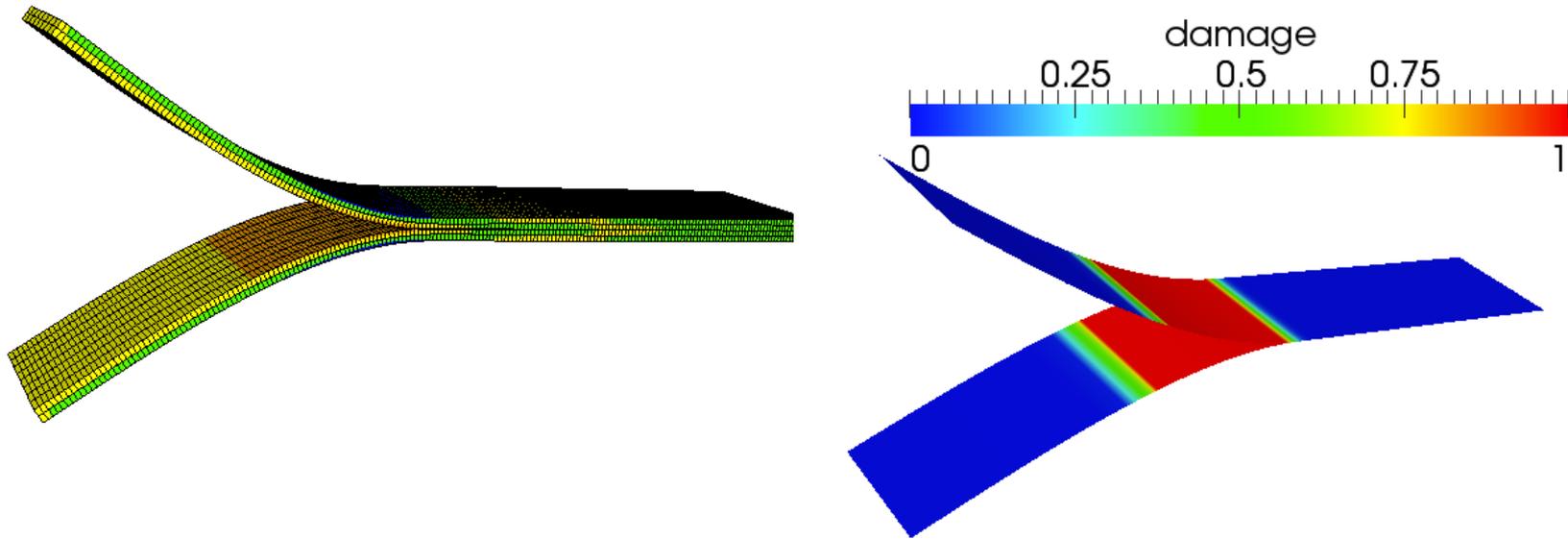


M. A. Gutierrez. Energy release control for numerical simulations of failure in quasi-brittle solids. Communications in Numerical Methods in Engineering, 20(1):19–29, 2004



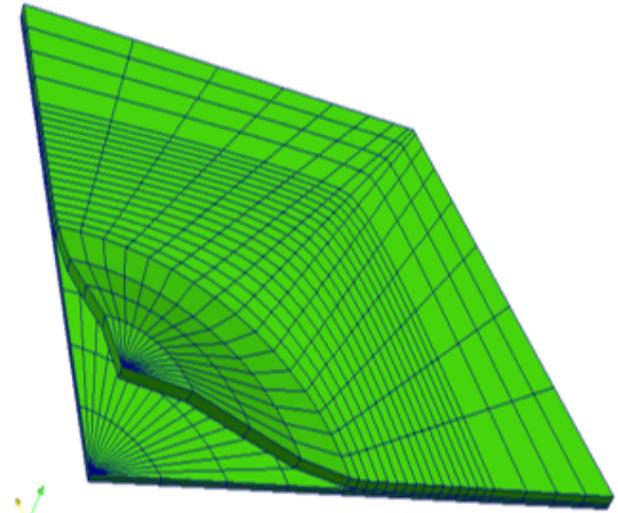
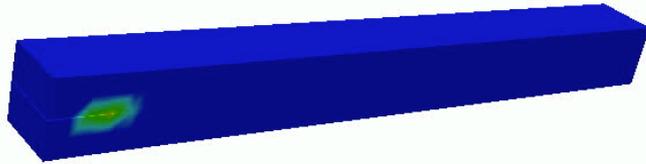
G. Wimmer and H.E. Pettermann. A semi-analytical model for the simulation of delamination in laminated composites. Composites Science & Technology, 68(12):2332 – 2339, 2008.

# Isogeometric cohesive elements: 3D example with shells

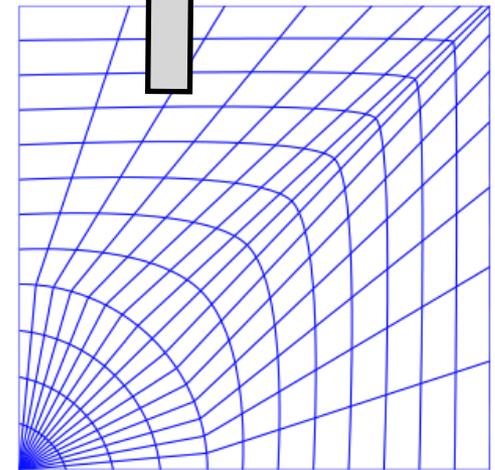
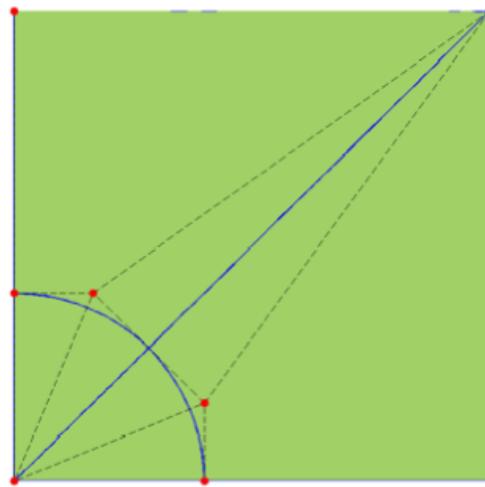


- Rotation free B-splines shell elements (Kiendl et al. CMAME)
- Two shells, one for each lamina
- Bivariate B-splines cohesive interface elements in between

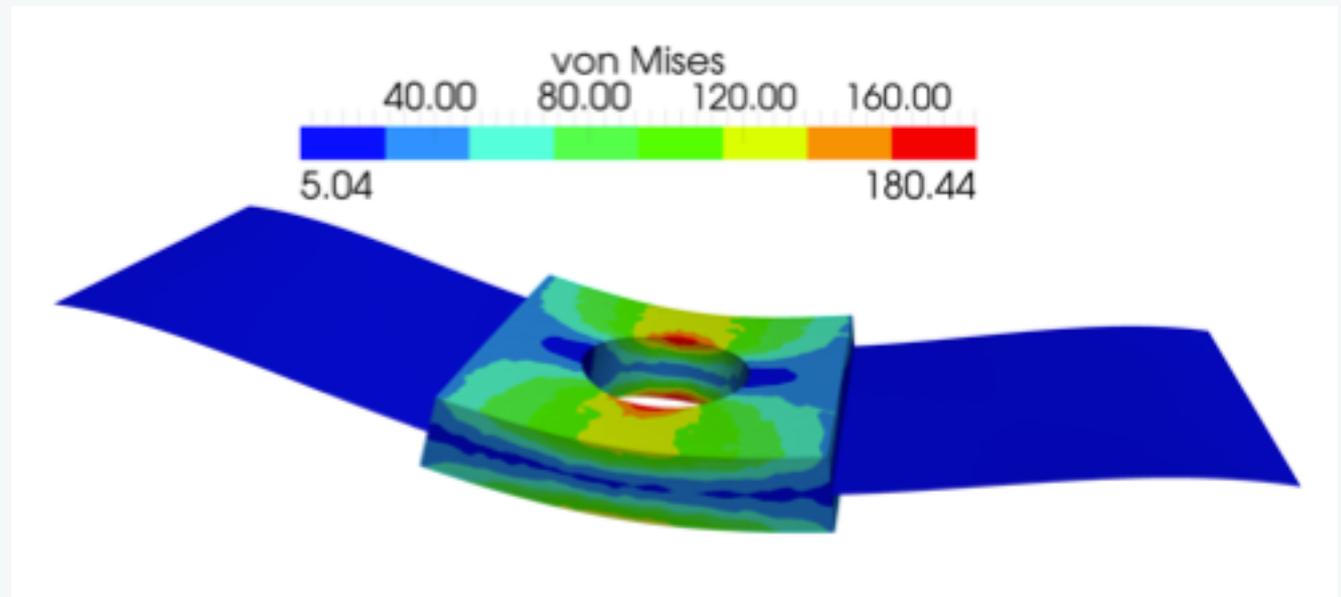
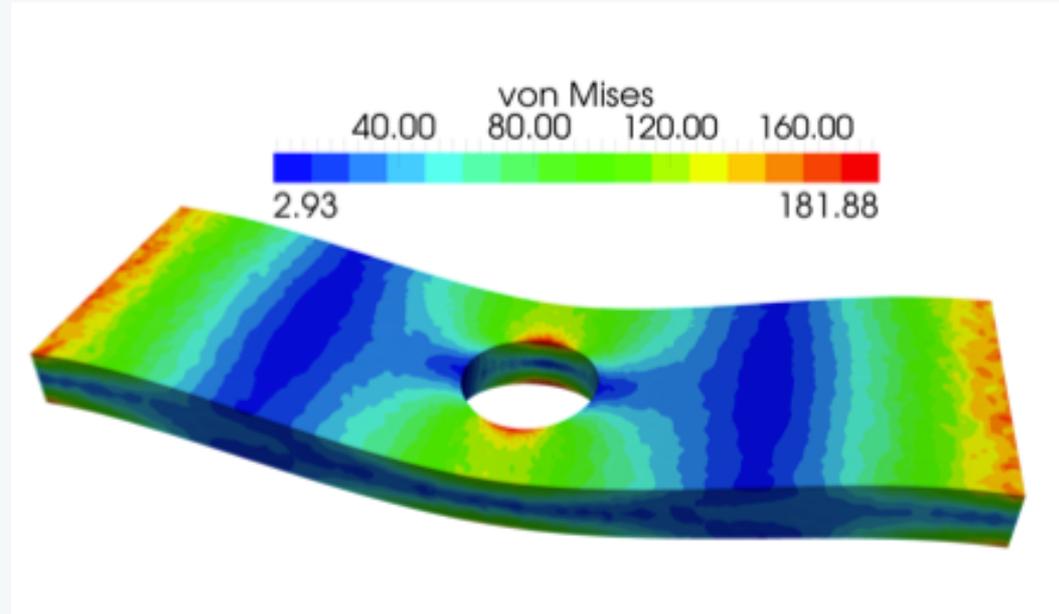
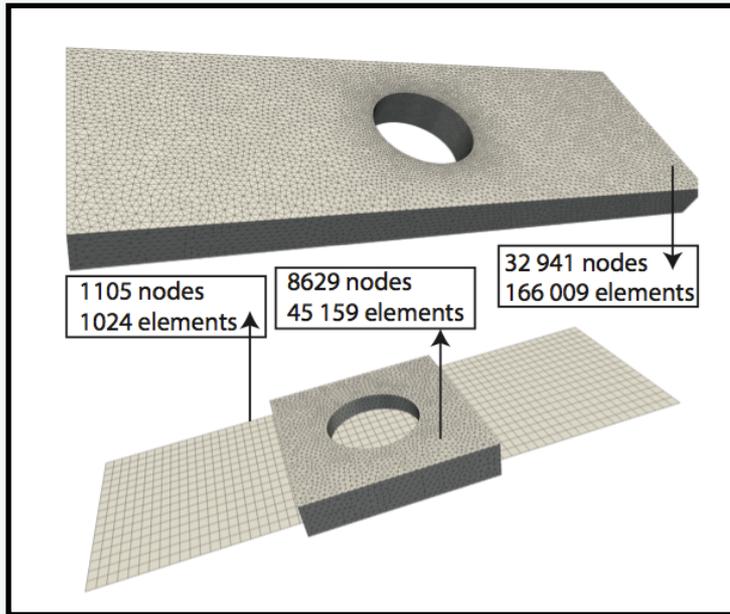
# Isogeometric cohesive elements: 3D examples



- cohesive elements for 3D meshes the same as 2D
- large deformations
- suitable: delamination buckling analysis



# Isogeometric plate and 3D FEM coupling



# Issues

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# Patch

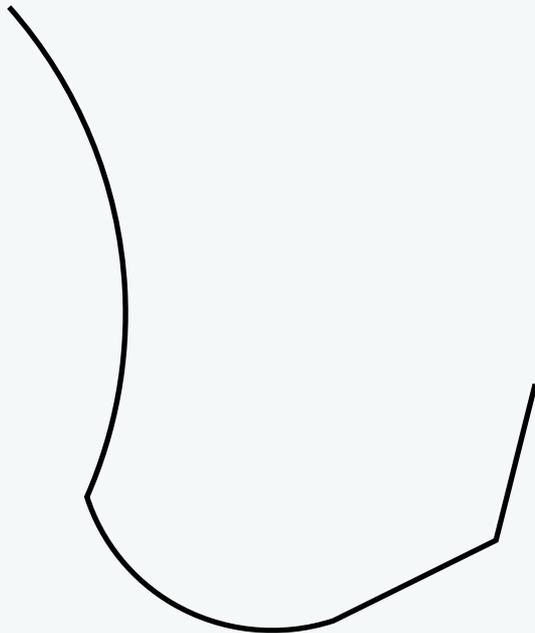
$$\Xi = \{0, 0, 0, 1/2, 1, 1, 1\}$$

$$\Xi^1 = \{0, 0, 0, 1/2, 1, 1, 1\}$$

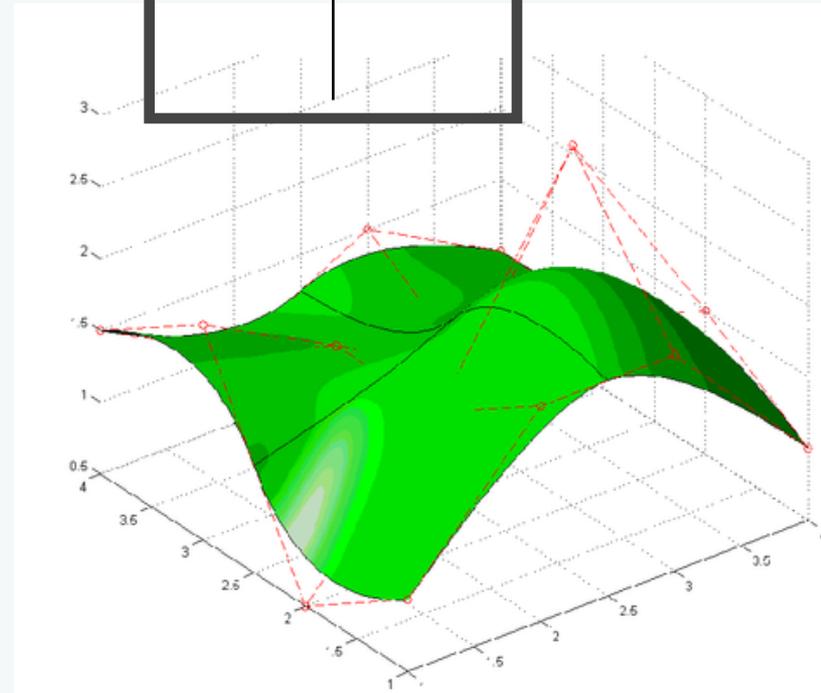
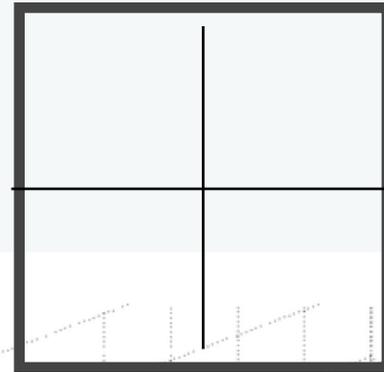
$$\Xi^2 = \{0, 0, 0, 1/2, 1, 1, 1\}$$



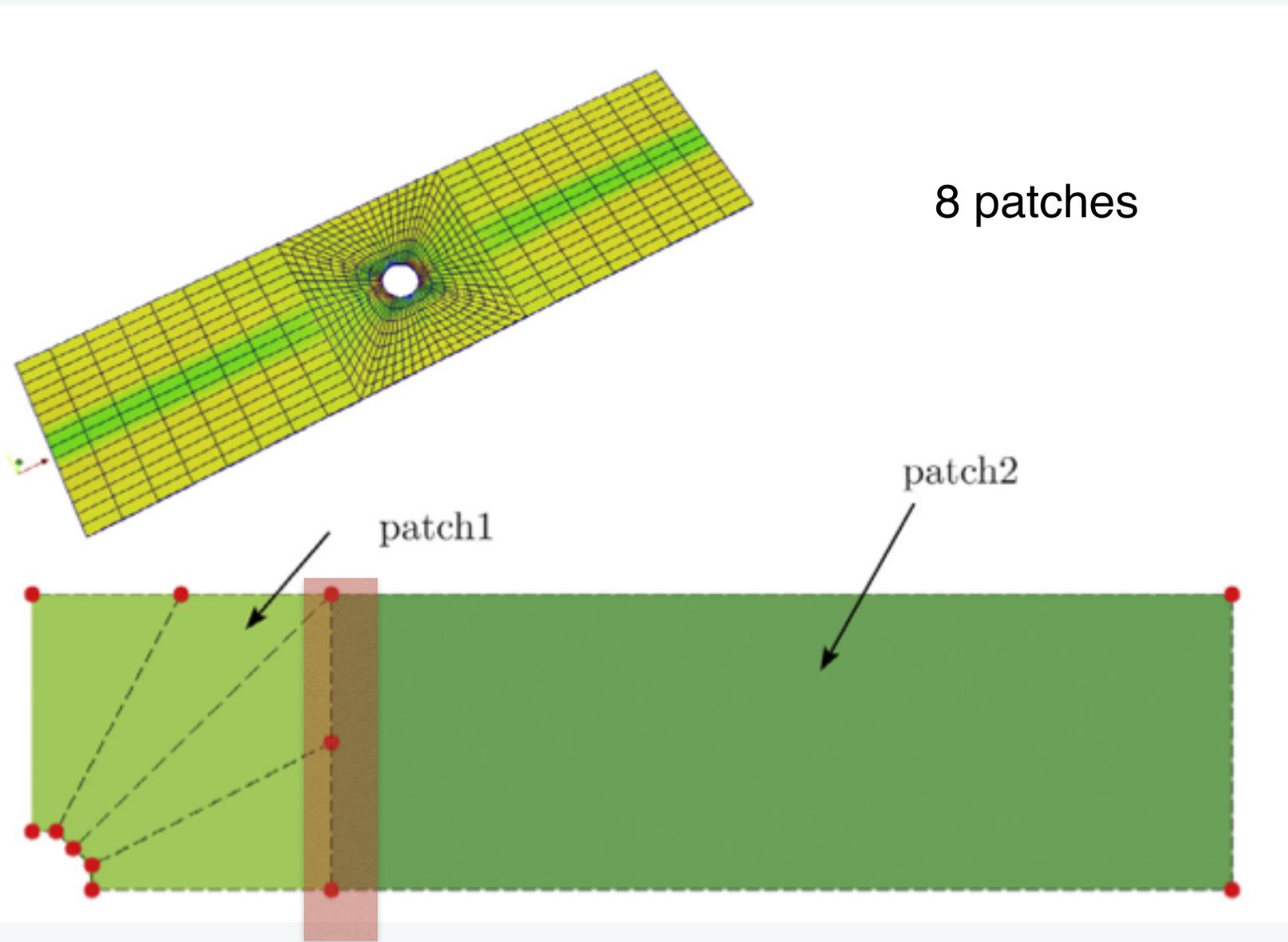
parameter space



physical space

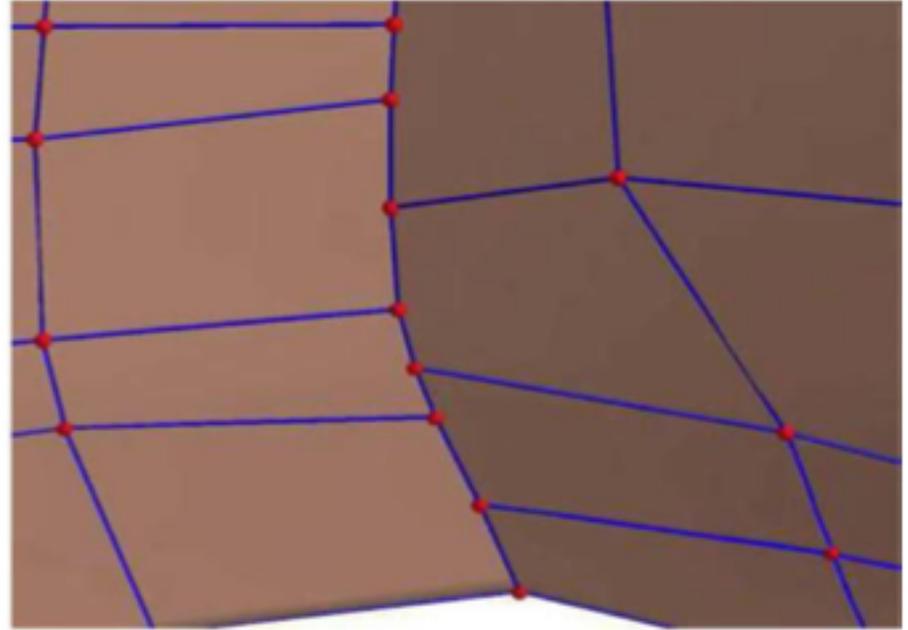
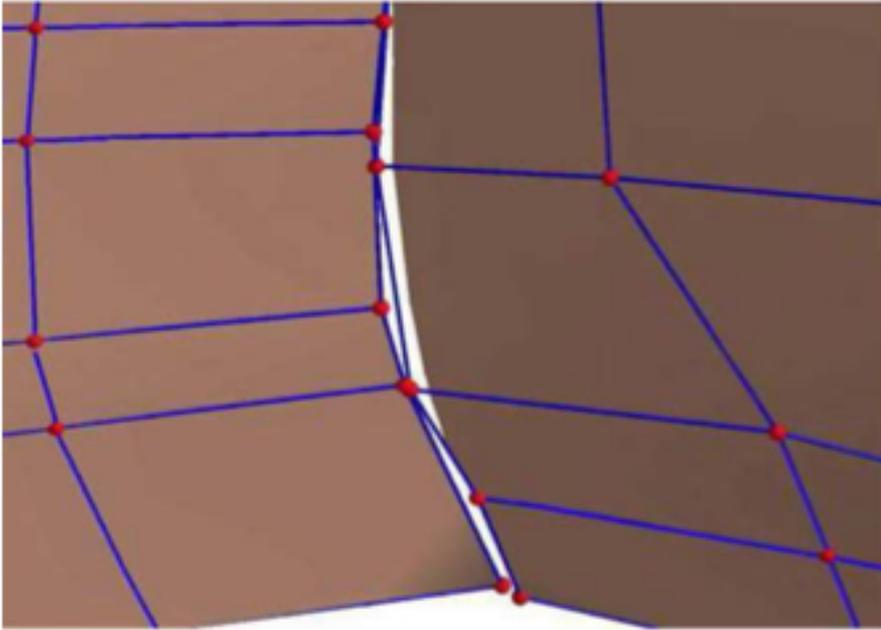


# Multipatch NURBS



# Multipatch NURBS

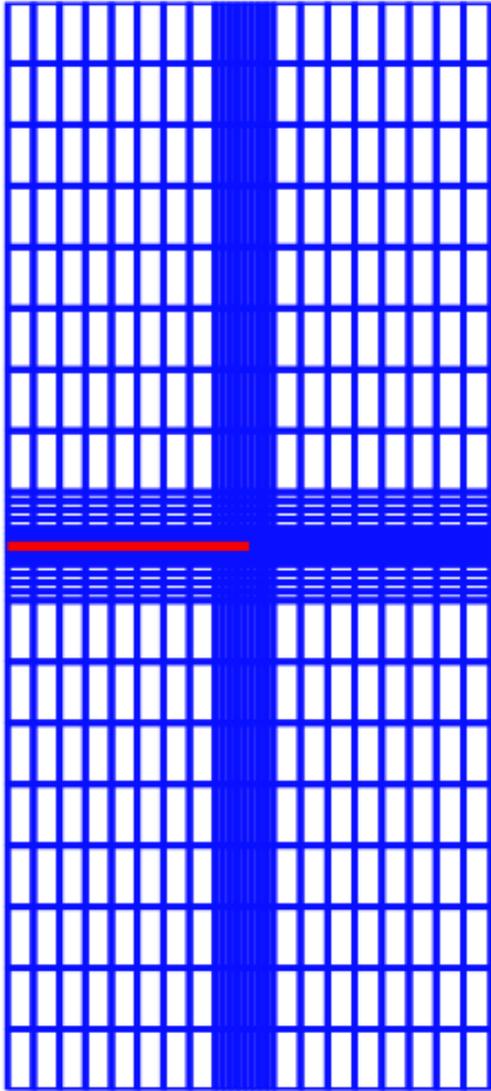
patch2



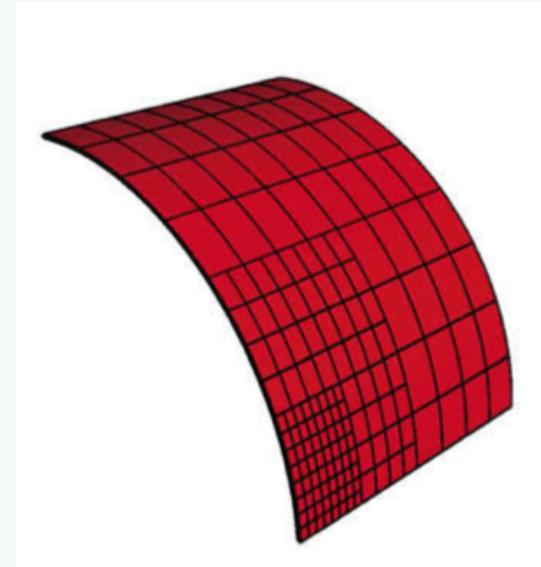
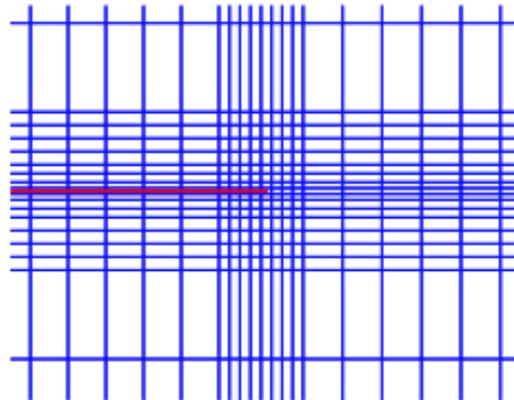
patch1

T-splines

# Local refinement



Solutions: Hierarchical B-splines and T-splines



# Summary

- B-splines/NURBS/T-splines not only for design but also for analysis
  - High order continuity: plate/shell theories, gradient elasticity/damage
  - Less prone to locking compared to low-order Lagrange elements
  - NURBS of any order achieved with a simple recursion relationship
  - Direct link to CAD: optimisation problems
  - Smooth geometries: contact problems
- 
- Elaborated enforcement of essential boundary conditions
  - Require knowledge on CAD
  - More demanding than low order finite elements

